

Tanner Declaration Exhibit B

WinLok 2.0

Operation Manual

7 JANUARY 2007

WinLok 2.0

*Digital Model Railroad
Command Control Software
for Windows*

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Table of Content

INTRODUCTION:

CAPABILITIES OF WINLOK 2.0	2
SYSTEM-REQUIREMENTS	2
LICENSE AGREEMENT	3
COPY PROTECTION	3
LIMITED WARRANTY	3
LIABILITY	3
TRADEMARKS	3

1. DATABASE SYSTEM

1.1. DATABASE STRUCTURE, BROWSER	4
1.2. BUTTON BAR	5
1.3. INPUT-WINDOW	6
1.3.1 ITEM / INVENTORY INPUT	6
1.3.2 SWITCHES & SIGNALS / SOLENOID DEVICE INPUT	7
1.3.3 LOCOMOTIVE INPUT-WINDOW	9
1.3.4 FEED-BACK SENSOR INPUT.	12
1.3.5. ROUTE ASSIGNMENT INPUT "MEMORY"	15
1.3.6. TRACK ELEMENT INPUT	21
1.3.7. TIMETABLE-INPUT	22
1.4. ADVICE FOR YOUR DATA-PROTECTION	23

2. LOCO-CONTROLLER "CAB-CONTROL" (THROTTLE)

2.1. CREATE CONTROLLER	24
2.2. SETUP	25
2.2.1. ENGINES AND TIMETABLE-SELECTION	25
2.2.2. SPEED-SELECTION	28
2.2.3. FUNCTIONS	29
2.2.4. STOP	29
2.2.5. DIRECTION CHANGE	29
2.2.6. TIMETABLE-LED	29
2.3. CLOSE CONTROLLER	30

3. SWITCH-BOARD

3.1. CREATE SWITCH-BOARD	31
3.2. SWITCH-BOARD SETUP PROCEDURES.	31
3.2.1. ASSIGN SOLENOID DEVICES	31
3.2.2. SWITCH SOLENOID	33
3.3. CLOSE SWITCH-BOARD	33

4. ROUTING-BOARD "MEMORY"

4.1. CREATE MEMORY	35
4.2. MEMORY SETUP PROCEDURES.	
4.2.1. ASSIGN BUTTONS	35
4.2.2. ACTIVATE ROUTES	37
4.3. CLOSE MEMORY	37

5. LAYOUT / TRACK DIAGRAM

5.1. SELECT LAYOUT / TRACK DIAGRAM	39
5.2. CREATE NEW TRACK DIAGRAM	39
5.2.1. INITIAL EMPTY LAYOUT / TRACK DIAGRAM.	39
5.3. PROGRAMMING OF INDIVIDUAL DIAGRAM ELEMENTS	41
5.3.1. ACTIVATOR BUTTON SETUP	43
5.3.2. TEXT INPUT	45
5.3.3. INDEX LIGHTS SETUP	46
5.3.4. COPYING OF PROGRAMMED DIAGRAM ELEMENTS.	
5.4. CLOSE TRACK DIAGRAM	49

6. TIMETABLE-SYSTEM

6.1. TIMETABLE-CONCEPT	50
6.2. ELEMENTS OF THE WINLOK 2.0 TIMETABLE-SYSTEMS	50
6.2.1. TIMETABLE-DATABASE	50
6.2.3. TIMETABLE-INTERPRETER (= ENGINEER)	51
6.2.4. OPERATION OF THE TIMETABLE-INTERPRETER.	52
6.3. COMMANDS OF THE TIMETABLE-PROGRAMMING	53
6.4. EXAMPLES	54
6.4.1. COMMUTER TRAIN SCHEDULE	54

7. MENU SYSTEM 59

7.1. GENERAL	59
7.2. DATABASE	60
7.3. LOCOMOTIVE CONTROLLER	61
7.4. SWITCH-BOARD	62
7.5. MEMORY / ROUTE ASSIGNMENT	63
7.6. LAYOUT / TRACK DIAGRAM	64
7.7. HELP	65

8. EXAMPLES 66

8.1. EXAMPLE OF ROUTE ASSIGNMENT PROGRAMMING.	66
8.1.1. BLOCK-SECTION	66
8.1.2. AUTOMATIC HIDDEN YARD	69
8.2. EXAMPLES FOR THE PROGRAMMING OF TRACK DIAGRAM ELEMENTS.	71
8.2.1. PROGRAMMING OF A SWITCH ELEMENT	71
8.2.2. PROGRAMMING OF ROUTE/BLOCK-OCCUPATION INDEX LIGHTS.	72
8.2.3. PROGRAMMING OF A RAILROAD-CROSSING BLINKING LIGHT	73
8.2.4. ADVANCED BLOCK-SECTION EXAMPLE. USING MARKLIN S88 MODULE	74

APPENDIX I: INSTALLATION OF WINLOK ON HARD-DRIVE 82

A) NEW-INSTALLATION	82
B) UPGRADE FROM VERSION 1.5	83

APPENDIX 2: 84

WINLOK DRIVERS 84

A.2.1 DRIVER FOR MARKLIN DIGITAL, MARKLIN DIGITAL= AND ARNOLD DIGITAL.	84
A.2.1.1 DRIVER PULL-DOWN MENU.	84
A.2.1.2 COMMUNICATION PORT SELECTION	85

A.2.1.3 SEND-PARAMETER 85

A.2.1.4 FUNCTION ALLOCATION. (MARKLIN 80F ONLY)	87
A.2.1.5. CONNECTION OF THE INTERFACES TO THE COMPUTER	87
A.2.1.6. COMMUNICATION-PROBLEMS	87
A.2.1.7 ABOUT.....	87
A.2.2. DRIVER FOR FLEISCHMANN FMZ	88
A.2.3. DRIVER FOR TRIX SELECTRIX	88
A.2.3.3. INTERFACE-DELAY	89
2.3.4. SET SYSTEM DATA	90
2.3.5. SELECT PREFERENCES	90
2.3.6. ABOUT SELECTRIX	91
A.2.4. DRIVER FOR LENZ DIGITAL PLUS	91
A.2.5. DRIVER FOR ZIMO DIGITAL-SYSTEM M1000	2
A.2.5.1 COMMUNICATION PORT SELECTION	92
A.2.5.2 SEND PARAMETER:	92
A.2.5.3 BASIC DATA:	92
A.2.5.4 CONDITIONING:	92
A.2.5.5 ABOUT....	92
A.2.6. TEST-DRIVER	94
A.2.7 TANNERSOFT MULTIDRIVE	95
A.2.7.1 DRIVER PULL-DOWN MENU.	95
A.2.7.2 DRIVER ALLOCATION	95
EXAMPLE:	96
A.2.7.3 ABOUT MULTIDRIVE	97
A.2.8.. TANNERSOFT DIRECTDRIVE.	98
A.2.8.1. DRIVER PULL-DOWN MENU.	98
A.2.8.2. SELECT COMPORT AND BAUD-RATE.	99
A.2.8.3. ADDRESSES	
A.2.8.4. SOLENOID/ACCESSORY DECODER PROGRAM-INPUT.	101
A.2.8.5. PROGRAMMER FOR MARKLIN, ARNOLD, LENZ...	102
A.2.8.6 PROGRAMMER FOR DIGITRAX DECODERS	105
A.2.8.8 DECODER SELECTION	109
A.2.9 DIGITRAX LOCONET™ DRIVER	110
A.2.9.1 DRIVER PULL-DOWN MENU.	110
A.2.9.2. SELECT SERIAL PORT	111
2.9.3 LOCONET ADAPTATION A	111
A.2.9.3 DISPATCH ADDRESS	112
A.2.9.4 ABOUT DIGITRAX DRIVER	113
A.2.9.5 NOTE FOR THE PROGRAMMING OF DECODERS:	113
A.2.9.6 WINLOK AND LOCONET COMMUNICATION	114

A.2.10 DRIVER FOR DIGIT99 FOR PARALLEL PORT 117
 A.2.10.1 COMMUNICATION PORT: 117
 A.2.10.2 INTERFACE DELAY: 117
 A.2.10.3 SOLENOID PROGRAMMER: 117
 A.2.9.4 ABOUT..... 117

APPENDIX 3: 118

A.3.1 DRIVER PROGRAM 118

APPENDIX 4: 122

SYNTAX COMMANDS FOR DEVICE SETUP 122
 A.4.1. SETUP OF LOCOMOTIVES 122
 A.4.1.1 SPEED-SETTINGS 122
 A.4.1.2 TIME-DELAY 123
 A.4.2 ROUTE ASSIGNMENT 124
 A.4.3 SETUP OF TRACK-DIAGRAM ELEMENTS 125

APPENDIX 5: 126

SYNTAX PROVISIONS FOR WINLOK 2.0 TIMETABLES 126
 A.5.1. STANDARD-LIBRARY 127
 A.5.1.1. OVERVIEW AND VARIABLES 127
 A.5.1.2. OPERATORS 129
 A.5.1.3. FUNCTIONS 140
 A.5.2. WINLOK 2.0 FUNCTION-LIBRARY 169
 A.5.2.1. CONSTANTS 169
 A.5.2.2. FUNCTIONS 170

Introduction:

WinLok 2.0 is a Windows 3.1 based program to control digital equipped Model-railroad systems with the computer. This Version supports following Digital Command Systems:

From Serial Port:

- Arnold Digital & Märklin Digital = support of 4 functions (crane, turntable, dancecar etc.)
- Märklin Digital
- Märklin 80f
- ZIMO
- Trix-Selectrix
- DirectDrive

Supporting the NIMRA DCC digital packet format. NMRA F7 or F8 Booster. Use full DIGITRAX decoder capability with DB100 , 14,28 and 128 Speed-steps. It will program and support following loco-decoders simultaneously:
 Any DIGITRAX with 1 to 3 functions, Lenz LE100S,-R / Lenz LE100M, Märklin c82 with 4 functions and ARNOLD

Digitrax Loconet™ Bus allows simultaneous operation of WinLok as "dispatcher" and handhold throttles for the engineers. Great for multiple person operation and club-layout.

From Parallel Port:
 Digit 99

The low cost, Do it yourself System. By Wolfgang Horn of Modellbahn Elektronik.

MULTIDRIVE.....

Operate any of the above Digital Command Systems simultaneously. Requires one RS232 Serial Port and/or Parallel Port, and the appropriate booster and/or Command Control equipment for each system.

A.2.6. Test-Driver

The Test Driver serves the purpose of testing the operation of WinLok without the need to hook up to a interface and digital-system. Furthermore all driver-specific data can be changed to simulate any digital-system.
See figure A.2.6.1. Driver Data Input.

Set-up Driver Data

By clicking on this bar you open a new window for input of data specific to your digital system. Enter data with the keyboard and mouse.

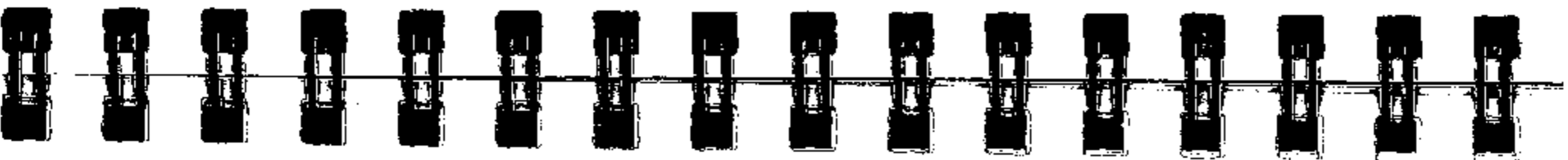
Figure A.2.6.1 Driver Data Input

Enter all data correct (consult the manual of your digital model railroad system for capacity and hardware specifics) to ensure the proper function.

All data will be loaded and corresponding devices adjusted by WinLok when the track-power is turned ON the next time.

About TannerSoft

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A.2.7 TannerSoft MultiDrive

The TannerSoft MultiDrive provides the capability to control multiple digital model-railroad systems simultaneously. This enables for example, to operate a HO Mainline and a HOm logging RR with different systems. Or HO 3rail main and foreground while at the same time controlling a N scale background system. There are many combinations possible. Addresses may be defined free for each system and will then be translated into actual possible addresses.

A.2.7.1 Driver pull-down menu.

The WinLok Menubar displays the selected driver with the manufacturers logo.

DRIVER ALLOCATION ABOUT MULTIDRIVE

A.2.7.2 Driver allocation

By clicking on this bar you open a new window for input with the keyboard and mouse.

Driver..... Select the driver you wish to change the addresses for this purpose.

From WinLok addresses: Enter in these six fields the addresses of the locos, Solenoid devices and Feedback-sensors you like to have controlled by the selected driver. Make sure that no addresses are overlapping to an other driver since these addresses must be unique. Overlapping addresses will make corresponding drivers to react and can cause confusion and will result in faulty commands and errors.

To Driver addresses: No input is possible here. These actual min. and max values are read from the selected driver data and can not be exceeded. If you for example, enter 90 Loco addresses with a Marklin driver, the invalid addresses will be ignored.

Example:

You have a layout with a Digitrax Mainline and a Arnold HOM sideline which you like to control with WinLok simultaneously. Your PC also has two free RS232 ports available.

Install the MultiDrive with these two "Subdrivers" DirectDrive and Arnold Drive.

Important: You need the appropriate Command Control or Booster for each system connected to a different Com-port. Since you already use the Mouse, most likely on Com-1 and a modem on Com-3, you can use Com-2 and Com-4 which will possibly require the installation of a additional I/O Board with a minimum of one RS 232 connector.

Now set the addresses as follows:

Addresses Arnold drive:

WinLok	1	99	1	256	1	31
System	1	99	1	256	1	31

Addresses DirectDrive (DIGITRAX)

WinLok	101	199	257	512	32	62
System	1	99	1	256	1	31

This address setup results in controlling your HOM Arnold sideline with Loco addresses 1 - 99 while your Digitrax Mainline Locos respond to addresses from 101 to 199, yet there physical address is also 1 - 99. The same works with the solenoid decoders and feedback-modules.

Note: You don't have to fully extend each drivers address capacity. You could use Loco 1 - 20 from Arnold and Loco 21 - 40 with Digitrax. Just keep the possibility in mind, that a later expansion may require adjustment.

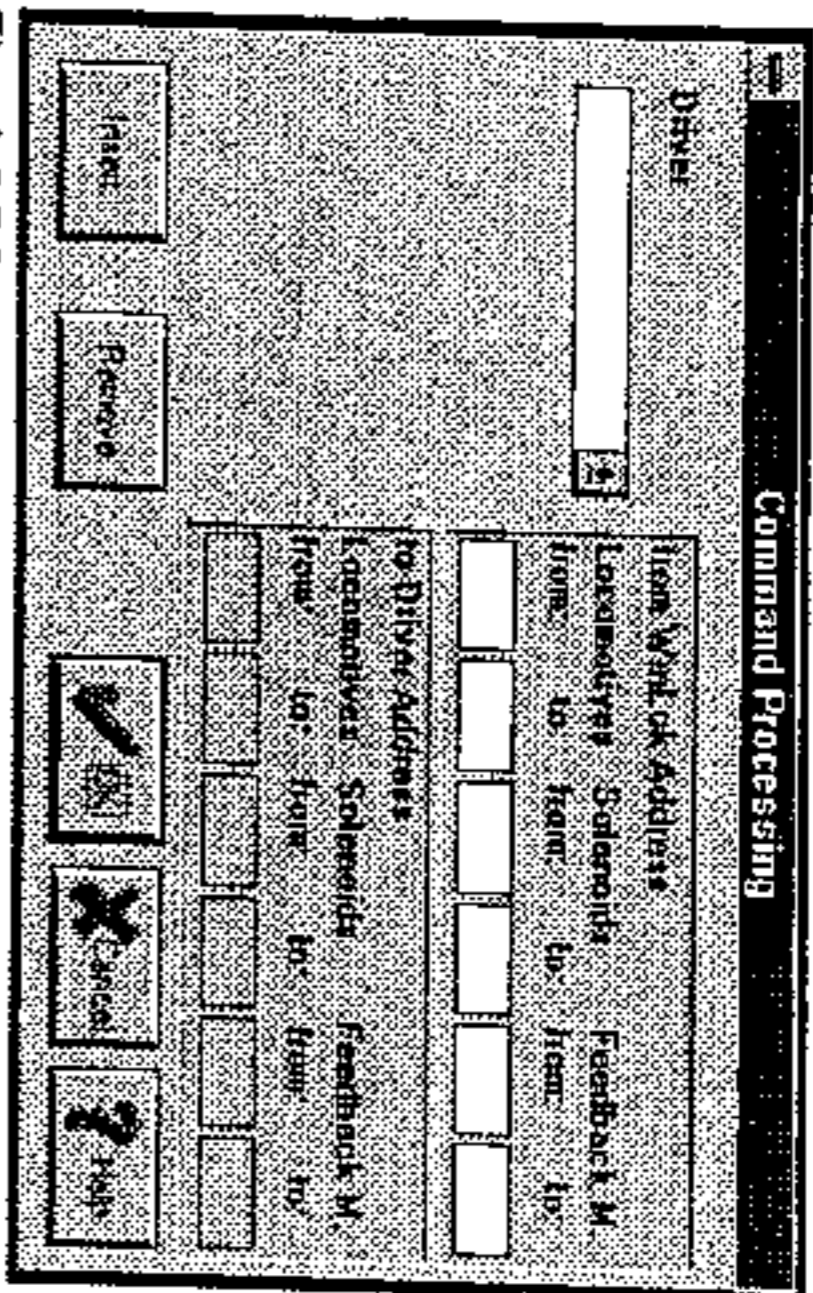
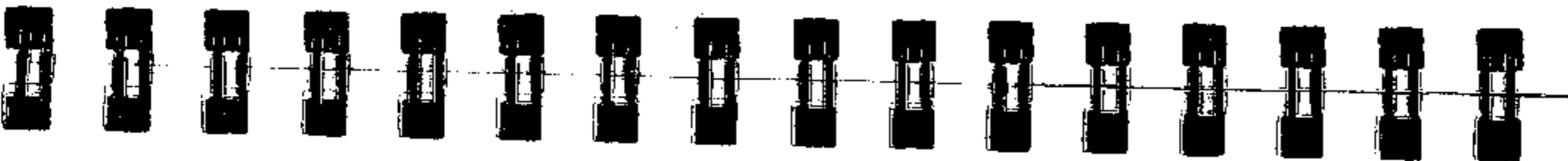


Fig: A 2.7.2

Insert: After clicking this button, a new box opens, displaying all available drivers for your selection. Highlight and click the OK button and the driver will be installed immediately and changes the WinLok menu accordingly.

Delete: Click on delete and the highlighted driver is deleted from MultiDrive. The address setup is saved and comes up with the next installation of the driver in MultiDrive.

A.2.7.3

About MultiDrive

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WinLok 2.0

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Digital Command Control Software for Windows

WinLok 2.0©

System-requirements.

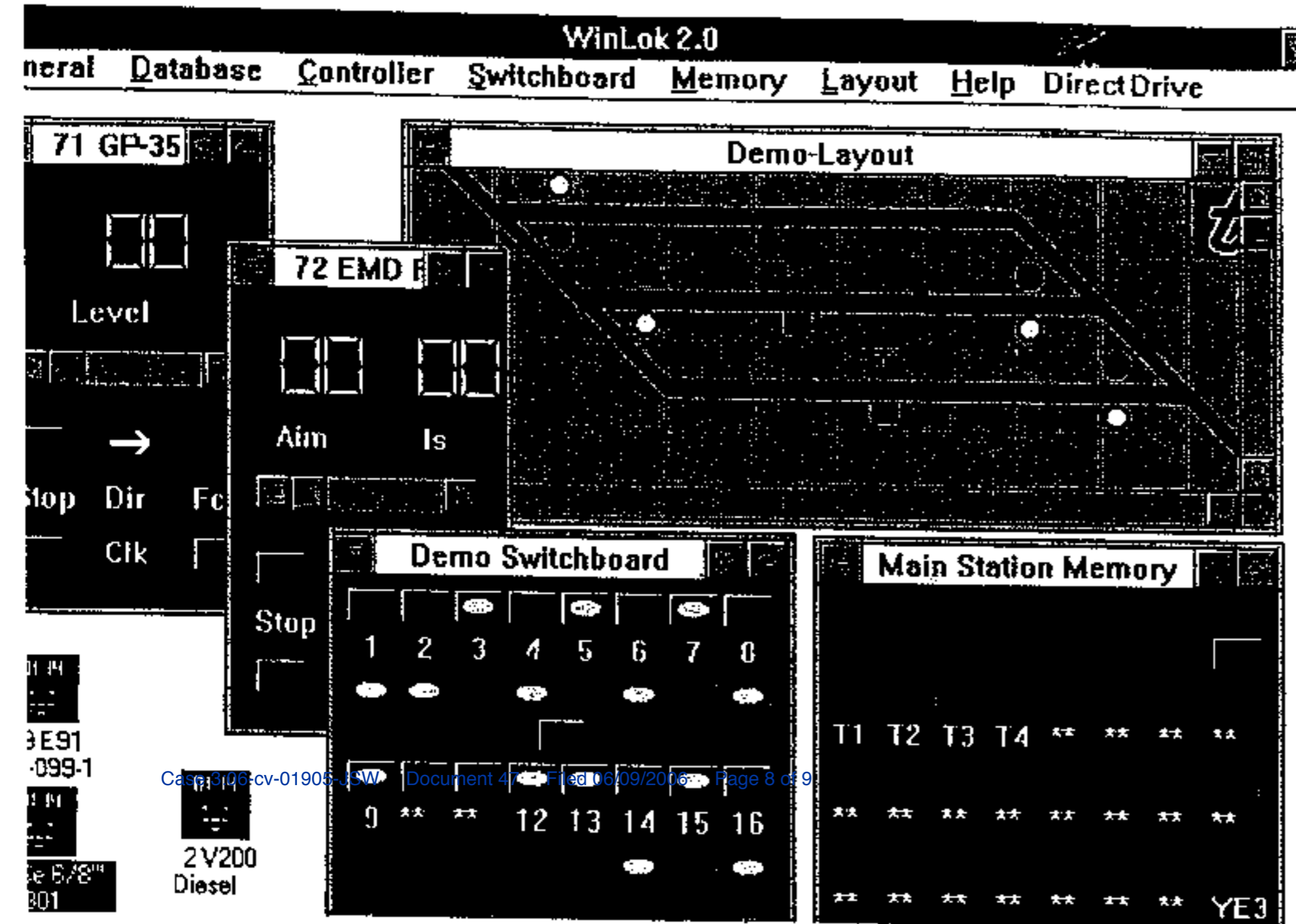
WinLok 2.0 requires a IBM compatible PC with the following minimum configuration:

- 80386 or better
- Processor
- 2MB RAM
- 1000000 Bytes
- 1MB required for
- Printer
- Hard Drive
- 4MB free space on
- Hard drive
- Mouse
- Windows
- 3.5" Drive
- Standard
- Expanded slots
- for
- MS-DOS
- Partial port

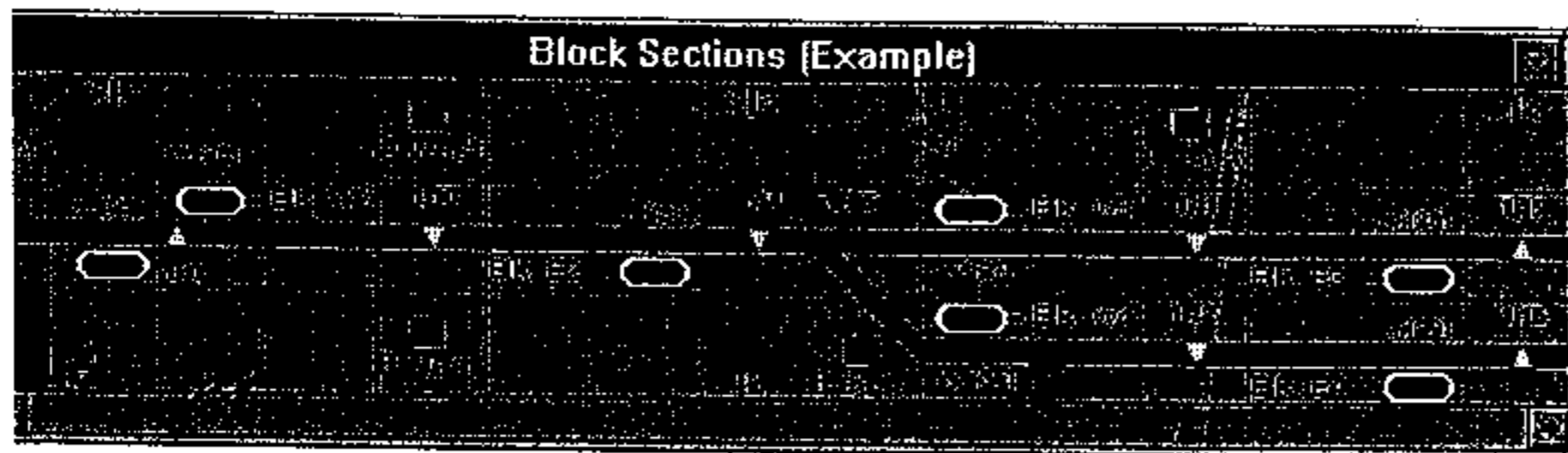
And for your Model Railroad:
One of the following Digital Command Control Systems:

- Digitrax
- LENZ
- Arnold
- NMRA DCC
- märklin
- TrixSelectrix
- Zimo

Contains one 3.5" Floppy and Documentation



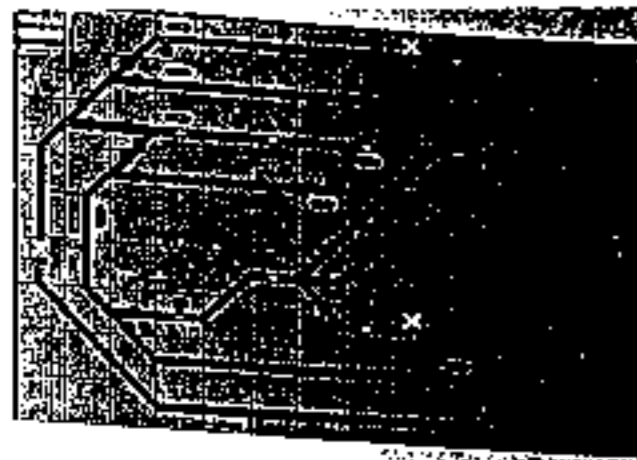
The New Dimension in Model Railroading



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PC
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WinLok 2.0

for Windows

NMRA DCC compatible

Introduction:

The software for the serious Model Railroad aficionado allows realistic operation of a layout with the aid of a computer. It controls all switches, routes and block occupation. It displays or individually created CTC panels for each yard or station. It assists in running trains with on screen throttles or use of hand throttle. It is simultaneous if selected command system is available. It interfaces with (Digitrax LocoNet-Bus, Lenz X-Bus, Märklin 80f control) with central unit and control 80 or 80f.

WinLok 2.0

is a Windows 3.1 based program to control digital equipped Model-railroad systems with the computer. This Version supports following Digital Command Systems:

From Serial Port:

- Arnold Digital & Märklin Digital =
- Märklin Digital
- Märklin 80f support of 4 functions (crane, turntable, dancecar, etc.)

• ZIMO

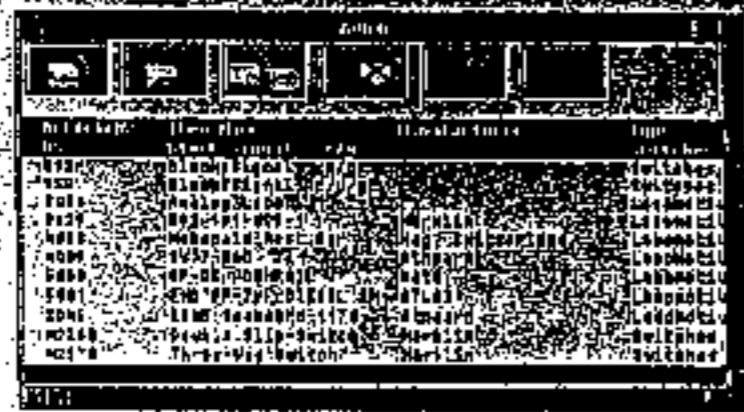
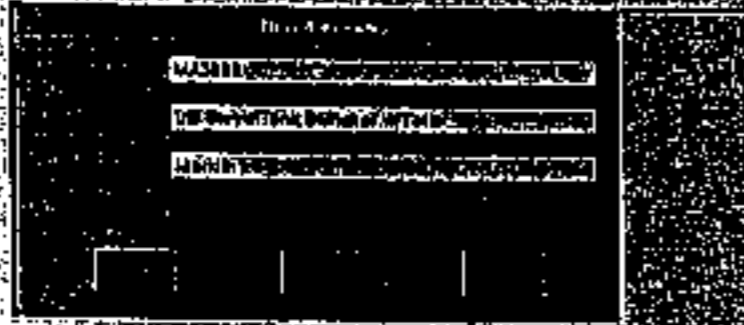
- Trix-Selectrix

- DirectDrive Supporting the NMRA DCC digital packet format, NMRA F7 or F8 Booster



DIGITRAX

Use full DIGITRAX decoder capability with DB100, 14, 28 and #28 Speed-steps. It will program and support following loco-decoders simultaneously: Any DIGITRAX with 1 to 3 functions, Lenz LE100S, R, Lenz LE100M, Märklin c82 with 4 functions and ARNOLD



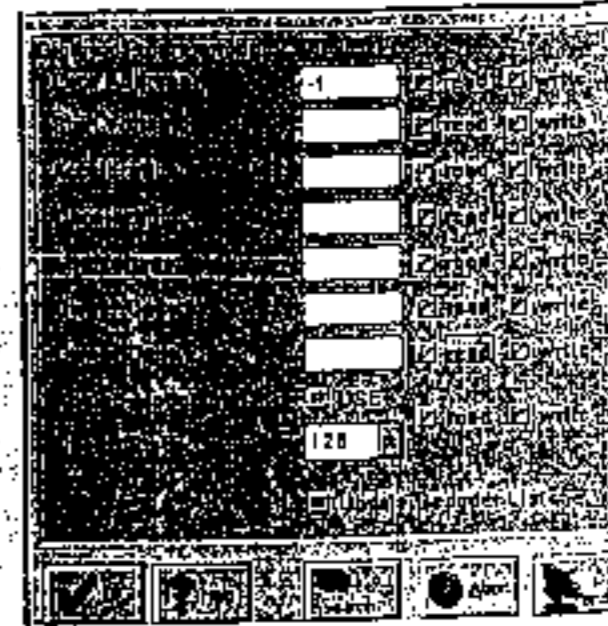
Digitrax LocoNet™ BUS allows simultaneous operation of WinLok as dispatchers and handhold interfaces for the engineers. Great for multiple person operation and club layouts.

Lenz X-Bus will basically perform the same as above.

From Parallel Port:

- Digit 99 The low cost, Do It Yourself System By Wolfgang Horn of Modellbahn Elektronik.

Operate any of the above Digital Command Systems simultaneously. Requires one RS232 Serial Port and/or Parallel Port and the appropriate booster and/or Command Control equipment for each system.



Features of WinLok 2.0

- Control a wide range of familiar digital control devices such as the Digit 99, Zimo, Selectrix and Memory with all their functions.
- Control on screen track diagrams (entire layout or sectional) with the computer and hand throttle.
- Interface with all digital bus systems and various signals and functions. Control the train with the click of the mouse.
- Control the Märklin 80f decoder programming feature for the Märklin, Lenz, Arnold and Märklin.
- Control the Märklin program (throttle, accelerate and decelerate) and the Märklin memory (power up or layout) with the computer and hand throttle.
- Program the Märklin decoder with speed controller, program the Märklin decoder with speed controller, switchboard and memory.
- Program the Märklin decoder with default settings for solenoid functions.
- Interface with the Märklin decoder.
- A booster is optional, possible simultaneous with another operation.
- Support of parallel (ISA based) interface cards for faster board operation with sensor modules.
- The amount of devices used is only limited by the memory of the computer system being used.
- Great flexibility, easy to learn program in WINDOWS.
- Full on screen and computer mouse supported.
- Up to 255 speed settings and 16 functions.
- High flexibility in selection of drivers for the operation of digital and digital Model Railroad Systems.